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Almost sure global well posedness for the radial nonlinear Schrödinger equation on the unit ball I: The 2D case

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Abstract

Our first purpose is to extend the results from [14] on the radial defocusing NLS on the disc in \( \mathbb{R}^2 \) to arbitrary smooth (defocusing) nonlinearities and show the existence of a well-defined flow on the support of the Gibbs measure (which is the natural extension of the classical flow for smooth data). We follow a similar approach as in [8] exploiting certain additional a priori space–time bounds that are provided by the invariance of the Gibbs measure.

Next, we consider the radial focusing equation with cubic nonlinearity (the mass-subcritical case was studied in [15]) where the Gibbs measure is subject to an \( L^2 \)-norm restriction. A phase transition is established. For sufficiently small \( L^2 \)-norm, the Gibbs measure is absolutely continuous with respect to the free measure, and moreover we have a well-defined dynamics. For sufficiently large \( L^2 \)-norm cutoff, the Gibbs measure concentrates on delta functions centered at 0. This phenomenon is similar to the one observed in the work of Lebowitz, Rose, and Speer [13] on the torus.

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1. Introduction

The purpose of this work is to establish global well-posedness results for the initial value problems associated to the defocusing (\( - \)) and focusing (\( + \)) nonlinear Schrödinger equation,

\[
\begin{aligned}
&i u_t + \Delta u \mp |u|^\alpha u = 0, \\
&u|_{t=0} = \phi
\end{aligned}
\]

(1)

with \( \alpha \in \mathbb{N} \) in the defocusing case, posed on the two-dimensional unit ball \( B_2 \subset \mathbb{R}^2 \), and with \( \alpha = \frac{4}{d} \) in the focusing case, posed on the \( d \)-dimensional unit ball \( B_d \subset \mathbb{R}^d \), \( d \geq 2 \). In both cases, we prescribe Dirichlet boundary conditions \( u(t) = 0 \) on \( \partial B_d \) for all \( t \in \mathbb{R} \).

In order to obtain results globally in time we will appeal to a probabilistic viewpoint, invoking the construction of an invariant Gibbs measure developed in the setting of nonlinear dispersive equations in the works [3–5]. To motivate our discussion below, let us first recall that a Hamiltonian system of the form

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\[
\frac{d}{dt} \left[ \begin{array}{c} p_i \\ q_i \end{array} \right]_{i=1,\ldots,n} = \left[ \begin{array}{c} -\partial H/\partial q_i \\ \partial H/\partial p_i \end{array} \right]_{i=1,\ldots,n}
\]

with \( H = H(p_1, p_2, \ldots, p_n, q_1, q_2, \ldots, q_n) \) is subject to the following invariance property: the Gibbs measure
\[
e^{-H(p,q)} d\mathcal{L}^{2n}(p,q)
\]
satisfies
\[
\int_A e^{-H(p,q)} d\mathcal{L}^{2n}(p,q) = \int_{\{(p(t),q(t)): (p(0),q(0)) \in A\}} e^{-H(p(t),q(t))} d\mathcal{L}^{2n}(p(t),q(t))
\]
for every measurable set \( A \subset \mathbb{R}^{2n} \) and \( t \in \mathbb{R} \), where \( \mathcal{L}^{2n} \) denotes Lebesgue measure and we use the abbreviation \( p = (p_1, \ldots, p_n), q = (q_1, \ldots, q_n) \).

The relevance of this observation to our present study is that the equation in (1) is of the form \( iu_t = \partial H/\partial u \), with conserved Hamiltonian
\[
H(\phi) = \frac{1}{2} \int_B |\nabla \phi|^2 dx + \frac{1}{\alpha + 2} \int_B |\phi|^\alpha + 2 dx.
\]

In order to access the invariance (3) of the Gibbs measure in this infinite dimensional setting, we shall consider a sequence of finite-dimensional projections of the problem (1), namely
\[
\begin{aligned}
iu_t + \Delta u \mp P_N (|u|^\alpha u) &= 0, \\
|u|_{t=0} &= P_N \phi
\end{aligned}
\]
for every integer \( N \geq 1 \), where \( P_N \) denotes the frequency truncation operator defined via the relation
\[
P_N \left( \sum_{n \in \mathbb{N}} a_n e_n(x) \right) = \sum_{\{n \in \mathbb{N}: z_n \leq N\}} a_n e_n(x),
\]
with \((e_n)\) the sequence of radial eigenfunctions and \((z_n^2)\) the sequence of associated eigenvalues of \(-\Delta\) with vanishing Dirichlet boundary conditions.

Solutions \( u_N \) to (4) exist globally in time and can be represented as
\[
u_N (t, x) = \sum_{\{n \in \mathbb{N}: z_n \leq N\}} u_n(t) e_n(x),
\]
and the equation may be written in the form (2) with
\[
p_i = \text{Re}(u_n(t)), \quad q_i = \text{Im}(u_n(t)).
\]

The Hamiltonian associated to the finite-dimensional projected problem (4) is then
\[
H_N(\phi) = \frac{1}{2} \sum_{z_n \leq N} z_n^2 |\hat{\phi}(n)|^2 + \frac{1}{\alpha + 2} \int_B |P_N \phi(x)|^\alpha + 2 dx.
\]

Furthermore, the flow map
\[
\phi_N \mapsto u_N(t)
\]
leaves invariant the Gibbs measure \( \mu_G \) corresponding to (4) defined by
\[
d\mu_G = e^{-H_N(\phi)} d\phi = e^{\mp \frac{1}{\alpha + 2} \|P_N \phi\|^\alpha + 2} d\mu^N_F,
\]
with \( \mu^{(N)}_F \) denoting the free probability measure induced by the mapping
\[
\omega \mapsto \frac{1}{\pi} \sum_{\{n \in \mathbb{N}: z_n \leq N\}} \frac{g_n(\omega)}{z_n} e_n, \quad \omega \in \Omega
\]
where \((g_n)\) is a sequence of normalized independent Gaussian random variables on a probability space \((\Omega, \mathcal{P}, \mathcal{M})\).
As noted in [3,6], when writing (5) one must take care to ensure (i) the $\mu_F$-a.s. existence of the norm $\|P_N\phi\|_{L^2_x}$ and (ii) the integrability of the density $e^{\pm \frac{1}{\sigma^2} \|P_N\phi\|_{L^2_x}^{\alpha+2}}$ with respect to the measure $\mu_F$. In both the defocusing and focusing cases, the first condition is satisfied as a consequence of estimates on the eigenfunctions. On the other hand, while the second condition is trivial in the defocusing setting, it is not satisfied in general when focusing interactions are present.

In the setting of focusing periodic NLS on the one-dimensional torus, the non-integrability of the density was overcome in the work of Lebowitz, Rose, and Speer [13] by restriction to a ball in the conserved $L^2_x$ norm. In particular, one fixes $\rho > 0$ and considers

$$d\mu_G = e^{\frac{1}{\sigma^2} \|P_N\phi\|_{L^2_x}^{\alpha+2}} \chi_{\{\|P_N\phi\|_{L^2_x} < \rho\}}(\phi) d\mu_F^{(N)}$$

which is again invariant under the evolution and can be normalized to a well-defined measure for all $\alpha \leq 4$ (the case $\alpha = 4$ requires $\rho$ sufficiently small).

1.1. Main results of the present work

In recent works [8,9] (see also [7]), we addressed the Cauchy problems corresponding to (1) for the defocusing nonlinear wave and Schrödinger equations on the unit ball of $\mathbb{R}^3$, establishing global well-posedness results for radial solutions with random initial data according to the support of the Gibbs measure (almost surely in the randomization) (see also [11]).

We say that functions $u, u_N : I \times B_d \to \mathbb{C}$ are solutions of (1), (4), respectively, if they belong to the class $C^t(I; H^s_x(B_d))$ for some $s < \frac{1}{2}$ and satisfy the associated integral equations

$$u(t) = \phi \pm i \int_0^t e^{i(t-\tau)\Delta} \left[|u(\tau)|^2 u(\tau)\right] d\tau, \quad t \in I,$$

and

$$u_N(t) = P_N\phi \pm i \int_0^t e^{i(t-\tau)\Delta} P_N \left[|u(\tau)|^2 u(\tau)\right] d\tau, \quad t \in I.$$ (7)

To proceed with our discussion, recall that we consider the sequence of finite-dimensional projections (4). Our estimates will typically be uniform in the truncation parameter $N$. To accommodate this, we will often make use of the probability measure $\mu_F$ induced by the mapping

$$\omega \mapsto \phi^{(\omega)} := \frac{1}{\pi} \sum_{n \in \mathbb{N}} \frac{g_n(\omega)}{z_n} e_n.$$

Note that with this notation, one has $\mu_F^{(N)} = P_N[\mu_F]$. Moreover, for each $N \geq 1$, the support of the Gibbs measure $\mu_G$ corresponds to the set

$$\{P_N\phi^{(\omega)} : \omega \in \Omega\}.$$

With this probabilistic framework in mind, our first main result, concerning the defocusing problem, takes the following form:

**Theorem 1.1.** Fix $\alpha \in 2\mathbb{N}$. With the above notations, for $N \in \mathbb{N}$, $\omega \in \Omega$, let $u_N$ denote the solution to (4) in the defocusing case on the two-dimensional unit ball with initial data $P_N\phi = P_N\phi^{(\omega)}$. Then almost surely in $\Omega$, for every $0 < T < \infty$ there exists $u_* \in C(I; H^s(\mathbb{R}^2))$, $s < \frac{1}{2}$ such that $u_N$ converges to $u_*$ in $C_I([0, T]; H^s(\mathbb{R}^2))$.

We remark that Theorem 1.1 was announced in [7]. The restriction on the nonlinearity to $\alpha \in 2\mathbb{N}$ is by no means essential, and serves only to simplify the estimates on the nonlinearity, avoiding technicalities due to fractional powers. The case $\alpha < 4$ was treated in [14].
The proof of Theorem 1.1 further develops the method of [8] and consists of an analysis of convergence properties of solutions to the truncated equations (4). In order to perform this analysis, we will make use of three key ingredients:

(i) A detailed study of embedding properties associated to the Fourier restriction spaces $X^{s,b}$ (see Lemma 2.3 and Lemma 2.5).
(ii) A probabilistic estimate demonstrating how the randomization procedure leads to additional $L^p_x L^q_t$ control, almost surely in the probability space (see Proposition 3.2).
(iii) A bilinear estimate of the nonlinearity enabling one to estimate interactions of high and low frequencies, allowing for a paraproduct-type analysis in the present setting (see Proposition 4.1).

The embeddings established in Lemma 2.3 and Lemma 2.5 use frequency decomposition techniques, exploiting the product structure inherent in the $L^4_t$ norm and the Plancherel identity. A technical tool used to estimate the frequency interactions at this stage are arithmetic estimates for the counting of lattice points on circles (see in particular Lemma 2.1).

On the other hand, the probabilistic $L^p_x L^q_t$ bounds of Proposition 3.2 make essential use of the fact that $u_N$ is a solution of (4). More precisely, the improvement in integrability follows from the invariance of the Gibbs measure and bounds for functions belonging to its support.

Turning to the bilinear estimate Proposition 4.1, the $X^{s,b}$ norm of certain products in the Duhamel formula are estimated by $X^{s,b}$ and $L^2_t H^s_x$ norms $(\gamma > 0$ small) of its factors – this involves appropriate high and low frequency localizations. The proof of this proposition is in the flavor of similar estimates in the $\mathbb{R}^d$ setting, with the additional component that the usual convolution identities are replaced with estimates on the correlation of eigenfunctions.

To conclude the proof of Theorem 1.1, the ingredients (i), (ii) and (iii) are combined in order to show that the approximate solutions $u_N$-almost surely converge in the space $X^{s,b}$ via a bootstrap-type argument. We refer the reader to Section 5 for the full details of the argument.

Our second main result, treating the focusing problem, is as follows.

Theorem 1.2. Set $\alpha = 2$. For each $N \in \mathbb{N}$, $\omega \in \Omega$ let $u_N$ denote the solution to (4) in the focusing case on the two-dimensional unit ball with initial data $P_N \phi = P_N \phi^{(\omega)}$ and subject to an appropriate $L^2$-norm restriction. Then for every $0 < T < \infty$, there exists almost surely $u_* \in C_t([0,T); H^s_x(B_2))$, $s < \frac{1}{2}$, such that $u_N$ converges to $u_*$ in $C_t([0,T); H^s_x(B_2))$.

The main additional issue in the proof of Theorem 1.2 is to show the $\mu_F$-integrability of the map

$\phi \mapsto e^{1/\tau \|\phi\|^{\alpha+2}_{L^2}} \chi_{\{\|P_N \phi\|_{L^2} < \rho\}}(\phi)$

provided that $\rho > 0$ is chosen sufficiently small. This result is stated in Proposition 6.1, and ensures a bound on the $L^2_x$-truncated Gibbs measures

$d\mu_G^{(N)} = e^{1/\tau \|\phi\|^{\alpha+2}_{L^2}} \chi_{\{\|P_N \phi\|_{L^2} < \rho\}}(\phi) d\mu_F^{(N)}$.

Once we have the invariant measure at our disposal, the convergence of the solutions of the truncated equations follows from the same argument as in the defocusing case for $\alpha = 2$, leading to a well-defined dynamics on the support of the modified Gibbs measure.

For subcritical nonlinearity $\alpha < 2$, the corresponding result was established in [15] (with arbitrary $L^2$-truncation).

In Remark 6.4 in Section 6, we will also comment on what happens for larger $L^2$-norm restriction $\rho$.

1.2. Outline of the paper

The remainder of this paper is structured as follows: in Section 2 we establish our notation and recall the definitions of the function spaces which will be used in the remainder of the paper. Section 3 is then devoted to the proof of a probabilistic estimate for solutions corresponding to initial data in the support of the Gibbs measure. In Section 4, we establish a key bilinear estimate on the nonlinearity, while the proof of Theorem 1.1 is contained in Section 5. We conclude by establishing Theorem 1.2 in Section 6.
2. Preliminaries

2.1. Notation

Let us now establish some brief notational conventions. Unless otherwise indicated, we will use the conventions $n \in \mathbb{N}, m \in \mathbb{Z}$, while capital letters $K, N$ and $M$ shall denote dyadic integers of the form $2^k$, $k \geq 0$. Throughout our arguments we will frequently make use of a dyadic decomposition in frequency, writing
\[
 f(x) = \sum_n \hat{f}(n)e_n(x) = \sum_{N \geq 1} \sum_{n - N} \hat{f}(n)e_n(x),
\]
where for each dyadic integer $N$, the condition $n \sim N$ is characterized by $N \leq n < 2N$ (likewise, we say $m \sim M$ if $M \leq |m| \leq 2M$). We shall also use the notation $(x) = (1 + |x|^2)^{1/2}$.

For each $n \in \mathbb{N}$, let $z_n \in \mathbb{R} \setminus \{0\}$ be such that $z_n^2$ is the $n$th eigenvalue of the Dirichlet Laplacian on $B_2$, and recall that $z_n$ satisfies
\[
 z_n = \pi \left(n - \frac{1}{4}\right) + O\left(\frac{1}{n}\right).
\]

Following the usual convention, we will often refer to $(z_n)$ as the sequence of frequencies for functions defined on the ball $B_2$. Moreover, let $e_n$ denote the $n$th radial eigenfunction, corresponding to the eigenvalue $z_n^2$. One then has
\[
 \|e_n\|_{L^p} \lesssim 1, \quad p \in [2, 4),
\]
\[
 \|e_n\|_{L^p} \lesssim \log(2 + n)^{1/4}, \quad p = 4,
\]
\[
 \|e_n\|_{L^p} \lesssim n^{1/2 - \frac{1}{p}}, \quad p \in (4, \infty).
\]

We now state a basic probabilistic estimate for Gaussian random variables. In particular, if $(g_n)$ is a sequence of independent (normalized) complex Gaussians, then we have
\[
 \left\| \sum_n \alpha_n g_n(\omega) \right\|_{L^q(d\omega)} \lesssim \sqrt{q} \left( \sum_n |\alpha_n|^2 \right)^{1/2}.
\]

Moreover, if $X(\omega)$ is a Gaussian process with values in some normed space $(E, \| \cdot \|)$, of finite expectation $\mathbb{E}_\omega[\|X\|]$, it follows that
\[
 \int e^{\left(\frac{\|X\|}{\delta\mathbb{E}_\omega[\|X\|]}\right)^2} < C
\]
and hence
\[
 \mathbb{P}_\omega[\|X\| > t\mathbb{E}_\omega[\|X\|]] \lesssim e^{-ct^2}, \quad t > 1.
\]

The results and analysis in this section appear basically in [14] and are repeated here in a form suitable for our presentation and in the interest of being self-contained.

2.2. Arithmetic estimates

As usual in the study of nonlinear Schrödinger equations on bounded domains (e.g. the case of tori treated in [3, 4]) an essential component of our analysis will rely upon arithmetical bounds for the sequence of frequencies. In particular, we shall use the following:

**Lemma 2.1.** There exists $c > 0$ such that for every $R > R_1 \gg 1$ and all boxes $Q \subset \mathbb{R}^2$ of size $R_1$, we have
\[
 \left| \{(n_1, n_2) \in \mathbb{Z}^2 : n_1^2 + n_2^2 = R^2, (n_1, n_2) \in Q\} \right| \lesssim \exp\left(\frac{\log R_1}{\log \log R_1}\right).
\]


Proof. Let $R_1 < R$ be given. Suppose first that $R_1$ and $R$ satisfy $R^{1/3} \lesssim R_1$. Note that factorization in the Gaussian integers $\mathbb{Z} + i\mathbb{Z}$ implies the bound
\[
\left\{ (n_1, n_2) \in \mathbb{Z}^2 : n_1^2 + n_2^2 = R^2 \right\} \leq \exp(\left\{ \text{Gaussian prime factors of } R^2 \right\}) < \exp \frac{\log R}{\log \log R}.
\] (13)
Since $\log R \sim \log R_1$, the inequality (12) now follows from (13).

On the other hand, suppose that $R_1 \lesssim R^{1/3}$. It then follows by Jarnick’s theorem for lattice points on circles that the left-hand side of (12) is at most 2, which gives the claim in this case. \[\square\]

Lemma 2.2. Let $\zeta_n^2$ be the $n$th eigenvalue of the Dirichlet Laplacian on $B_2$ and let $Q \subset \mathbb{R}^2$ be a box of size $R_1$. Then for any $\ell \in \mathbb{R}^+$,
\[
\left\{ (n_1, n_2) \in \mathbb{Z}^2 : |\zeta_{n_1}^2 + \zeta_{n_2}^2 - \ell| < 1, \ (n_1, n_2) \in Q \right\} \lesssim \exp \left( c \frac{\log R_1}{\log \log R_1} \right).
\]
Proof. According to (8), $\zeta_n^2 = \pi^2 (n - \frac{1}{4})^2 + O(1)$. Therefore the equation $|\zeta_{n_1}^2 + \zeta_{n_2}^2 - \ell| < 1$ implies
\[
\pi^2 \left( n_1 - \frac{1}{4} \right)^2 + \pi^2 \left( n_2 - \frac{1}{4} \right)^2 = \ell - O(1),
\]
\[
(4n_1 - 1)^2 + (4n_2 - 1)^2 = \frac{16\ell}{\pi^2} - O(1)
\]
and we can apply Lemma 2.1 setting $n_1' = 4n_1 - 1, n_2' = 4n_2 - 1$. \[\square\]

2.3. Description of the $X^{s,b}$ spaces

Fix $I = [0, T)$ with $0 < T < \frac{1}{2}$, and let $X^{s,b}(I)$ denote the class of functions $f : I \times B \to \mathbb{C}$ representable as
\[
f(t, x) = \sum_{n,m} f_{n,m} e_n(x) e(mt), \quad (t, x) \in I \times B
\] (14)
for which the norm
\[
\|f\|_{s,b} := \inf \left\{ \sum_{n,m} \langle \zeta_n \rangle^{2s} |\zeta_n^2 - m|^{2b} |f_{n,m}|^2 \right\}^{1/2}
\]
is finite, with the infimum taken over all representations (14), cf. [1,2]. Throughout the remainder of the paper, we will assume $0 < T < \frac{1}{2}$, unless otherwise indicated.

We now give two lemmas expressing some embeddings of the space $X^{s,b}$ which will be essential components of our analysis below. Similar estimates appear already in [14] (see in particular [14, Proposition 4.1]).

Lemma 2.3. Let $\frac{1}{4} < b < 1$ and $2 \leq p < 4$ be given. Then, letting $P_t f = \sum_{\zeta_n \in I} \hat{f}(n)e_n$, we have for $\epsilon > 0$, $f \in S$ and intervals $I \subset \mathbb{R}$,
\[
\|P_t f\|_{L^p_t L^4_x} \lesssim \begin{cases} |I|^\epsilon \|P_t f\|_{0,b} & \text{for } b > \frac{1}{2}, \\ |I|^{1-2b+\epsilon} \|P_t f\|_{0,b} & \text{for } b < \frac{1}{2}. \end{cases}
\] (15)
Proof. We begin by establishing the first inequality in (15), for which we shall compute the norm directly. Fix $\epsilon > 0$ and write
\[
P_t f(t, x) = \sum_{m \in \mathbb{Z}} \sum_{\zeta_n \in I} \hat{f}(m, n)e_n(x)e(mt) = \sum_m \left( \sum_{\zeta_n \in I} \hat{f}(m + [\zeta_n^2], n)e_n(x)e(\zeta_n^2 t) \right)e(mt).
\]
Performing a dyadic decomposition into intervals \( m \sim M \), we obtain
\[
\| P_I f \|_{L^p_t L^q_x} \lesssim \sum_M \| f_M \|_{L^p_t L^q_x}
\]
with
\[
f_M = \sum_{m \sim M} \sum_{z_n \in I} \hat{f}(m + [z_n^2], n) e_n(x) e(z_n^2 t) e(mt).
\]
We then have
\[
\| f_M \|_{L^p_t L^q_x} \lesssim \sum_m \left( \sum_{\ell} \left[ \sum_{z_n, z_n' \in I} \hat{f}(m + [z_n^2], n) \hat{f}(m + [(z_n')^2], n') e_n(x) e_n'(x) e^{i \ell t} \right] \right)^{1/2} \lesssim \sum_m \left( \sum_{\ell} \left[ \sum_{z_n, z_n' \in I} \hat{f}(m + [z_n^2], n) \hat{f}(m + [(z_n')^2], n') e_n(x) e_n'(x) \right] \right)^{1/2}
\]
where in obtaining the last inequality we used the Plancherel identity in the \( t \) variable.

Using the Cauchy–Schwarz inequality and Lemma 2.2,
\[
(16) \lesssim \sum_m \left( \sum_{\ell} \left[ \sum_{z_n, z_n' \in I} \hat{f}(m + [z_n^2], n) \hat{f}(m + [(z_n')^2], n') e_n(x) e_n'(x) \right] \right)^{1/2} \lesssim \sum_m \left( \sum_{\ell} \left[ \sum_{z_n, z_n' \in I} \hat{f}(m + [z_n^2], n) \hat{f}(m + [(z_n')^2], n') e_n(x) e_n'(x) \right] \right)^{1/2}
\]
where to obtain the last inequality we used the eigenfunction estimate (9).

Invoking the Cauchy–Schwarz inequality once more,
\[
(16) \lesssim |I|^\epsilon M^{\frac{1}{2}} \left( \sum_{m \sim M} \sum_{z_n \sim I} |\hat{f}(m + [z_n^2], n)|^2 \right)^{1/2} = |I|^\epsilon M^{\frac{1}{2}} \left( \sum_{m \sim M} \sum_{z_n \sim I} |\hat{f}(m, n)|^2 \right)^{1/2} \lesssim |I|^\epsilon M^{\frac{1}{2} - b} \| P_I f \|_{0,b}.
\]

On the other hand to obtain the second inequality in (15), a similar calculation yields
\[
\| f_M \|_{L^p_t L^q_x} \leq \sum_{z_n \in I} \left( \sum_{m \sim M} \hat{f}(m + [z_n^2], n) e(mt) \right) \| e_n(x) \|_{L^p_x} \lesssim M^{\frac{1}{2}} \sum_{z_n \in I} \left( \sum_{m \sim -M} |\hat{f}(m, n)|^2 \right)^{1/2} \lesssim |I|^{1/2} M^{\frac{1}{2} - b} \| P_I f \|_{0,b}.
\]

Thus from (17), (18)
\[
\| f_M \|_{L^p_t L^q_x} \lesssim \min \{ |I|^\epsilon M^{\frac{1}{2} - b}, |I|^\frac{1}{2} M^{\frac{1}{2} - b} \} \| P_I f \|_{0,b}
\]
and summation in \( M \) gives the desired estimates.
Remark 2.4. The estimates obtained in Lemma 2.3 also allow us to conclude

\[ \|f\|_{L^p_t L^4_x} \leq C \|f\|_{\epsilon,b} \quad \text{for } b \geq 1/2 \text{ and } p \leq 4 \]

and

\[ \|f\|_{L^p_t L^4_x} \leq C \|f\|_{1-2b+\epsilon,b} \quad \text{for } 1/4 < b < 1/2. \]

Indeed, appealing to the decomposition \( f = \sum_N P(N,2N)f \) with \( N \geq 1 \) dyadic and applying (15) on each interval \( I = [N, 2N) \) (with \( \tilde{\epsilon} = \epsilon/2 \)), we obtain

\[ \|f\|_{L^p_t L^4_x} \lesssim \sum_N N^{\epsilon/2} \|P(N,2N)f\|_{0,b} \lesssim \sum_N N^{-\epsilon/2} \|f\|_{\epsilon,b} \lesssim \|f\|_{\epsilon,b} \]

for \( b \geq 1/2 \). An identical calculation with an application of the second inequality in (15) in place of the first inequality of (15) gives the claim for \( 1/4 < b < 1/2 \).

As a consequence of Lemma 2.3, we have the following estimates on the nonlinear term of the Duhamel formula (7).

Lemma 2.5. For each interval \( I \subset \mathbb{R} \) and every \( b > \frac{1}{2}, \epsilon > 0 \), there exists \( C = C(b, \epsilon) > 0 \) such that

\[ \left\| P_I \left( \int_0^t e^{i(t-\tau)\Delta} f(\tau) \, d\tau \right) \right\|_{0,b} \leq C|I|^{2b-1+\epsilon} \|f\|_{L^4_t L^4_x}^{4} \cdot \frac{4}{4-b} \] (19)

Moreover, the inequality

\[ \left\| \int_0^t e^{i(t-\tau)\Delta} f(\tau) \, d\tau \right\|_{0,b} \leq C (\sqrt{-\Delta})^{2b-1+\epsilon} \|f\|_{L^4_t L^4_x}^{4} \cdot \frac{4}{4-b} \] (20)

also holds for all \( f \in S \).

Proof. We begin by showing (19), invoking the representation

\[ f(t, x) = \sum_{m,n} \hat{f}(m, n) e_n(x) e(mt) \]

and observing that the left-hand side of (19) is

\[
\left\| \sum_{m \in \mathbb{Z}, \, \overset{\scriptscriptstyle z_n \notin I}{z_n \in I}} \int_0^t e^{i(t-\tau)z_n^2} \hat{f}(m, n) e_n(x) e^{im\tau} \, d\tau \right\|_{0,b} = \left\| \sum_{m \in \mathbb{Z}, \, \overset{\scriptscriptstyle z_n \notin I}{z_n \in I}} \hat{f}(m, n) e_n(x) \cdot \frac{e(mt) - e(z_n^2 t)}{i(m - z_n^2)} \right\|_{0,b}
\]

\[
\lesssim \left( \sum_{m \in \mathbb{Z}, \, \overset{\scriptscriptstyle z_n \notin I}{z_n \in I}} \frac{|\hat{f}(m, n)|^2}{(m - z_n^2)^2(1-b)} \right)^{1/2} + \left( \sum_{z_n \in I} \left( \sum_m |\hat{f}(m, n)|^2 \right)^2 \right)^{1/2}
\]

\[
\lesssim \left( \sum_{m \in \mathbb{Z}, \, \overset{\scriptscriptstyle z_n \notin I}{z_n \in I}} \frac{|\hat{f}(m, n)|^2}{(m - z_n^2)^2(1-b)} \right)^{1/2}
\]

\[ = \| P_I f \|_{0,-(1-b)} \] (21)

where we have used Cauchy–Schwarz to obtain the second inequality.
By duality arguments followed by Hölder’s inequality combined with Lemma 2.3, we then have
\[
\| P_I f \|_{0, -(1-b)} = \sup \left\{ \left| \int P_I f(t, x) P_I g(t, x) \, dt \, dx \right| : \; g \in L^2, \; \| P_I g \|_{0, 1-b} \leq 1 \right\}
\leq \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2} \| P_I g \|_{\frac{4+\varepsilon}{4+\varepsilon}} \frac{4}{L_1^2} L_1^2
\lesssim |I|^{1-2(1-b)+\varepsilon} \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2} \| P_I g \|_{0, 1-b}
\lesssim |I|^{2b-1+\varepsilon} \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2}. \tag{22}
\]
The inequality (19) now follows by combining (21) and (22).

The proof of (20) proceeds in a similar manner. Arguing as above and using Remark 2.4, we obtain
\[
\left\| \sum_{n \in \mathbb{N}} \int_0^t e^{i(t-\tau)\frac{2}{N} \int f(m, n) e_n(x) e^{int} \, d\tau} \right\|_{-(2b-1+\varepsilon), b}
\lesssim \| f \|_{-(2b-1+\varepsilon), -(1-b)}
\leq \sup \left\{ \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2} \| g \|_{\frac{4+\varepsilon}{4+\varepsilon}} \frac{4}{L_1^2} L_1^2 : \; \| g \|_{2b-1+\varepsilon, 1-b} \leq 1 \right\}
\lesssim \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2} \| g \|_{2b-1+\varepsilon, 1-b}
\lesssim \| f \|_{\frac{4}{4+\varepsilon}} \frac{4}{L_1^2}
\]
from which the desired inequality (20) follows immediately. \( \square \)

3. Probabilistic estimates

In this section, we establish a collection of essential probabilistic estimates which will enable us to obtain long-time control over solutions to (4). We remark that these estimates are uniform in the truncation parameter \( N \); this uniformity is important in the convergence proof of the next section.

We begin by establishing an almost sure bound on initial data belonging to the support of the Gibbs measure \( \mu_G \).

**Lemma 3.1.** Fix \( s < \frac{1}{2} \). Then we have the bound
\[
\mu_F \left( \left\{ \phi : \; N_0^{-\frac{1}{2}} \| P_{\leq N_0} \phi \|_{H^s} > \lambda \right\} \right) \leq \exp \left( -\lambda^{-s} \right) \tag{23}
\]
for all \( N_0 \geq 1 \) sufficiently large, where \( \phi = \phi(\omega) = \sum_{n \in \mathbb{N}} g_n(\omega) e_n \).

**Proof.** Fix \( q_1 \geq 2 \) to be determined. The Tchebyshev and Minkowski inequalities together with the estimate (10) then imply that the left-hand side of (23) is bounded by
\[
\frac{N_0^{1-s} q_1}{\lambda q_1} \| P_{\geq N_0} \phi \|_{L^q_{t,x}(d\mu_F; H^s)} \lesssim \frac{N_0^{1-s} q_1}{\lambda q_1} \left( \sum_{n = N_0}^{\infty} g_n(\omega) e_n \right)_{L^2}^{q_1/2}
\lesssim \left( \frac{N_0^{1-s} q_1}{\lambda} \right) \left( \sum_{n = N_0}^{\infty} z_n^{-2(1-s)} \right)^{q_1/2}
\lesssim \left( \frac{\sqrt{q_1}}{\lambda} \right)^{q_1} \tag{24}
\]
where the summation in the third line is bounded by $N^{-1+2s}$ for $N_0$ sufficiently large, as a consequence of the asymptotic representation (8) for the sequence of eigenvalues $(\varepsilon_n)$. Optimizing (24) in $q_1$, we obtain the desired estimate (23). □

In particular, we note that Lemma 3.1 includes a description of the decay present when considering the restriction of $\phi$ to high frequencies. The next proposition is an essential ingredient and combines this type of probabilistic estimate with the invariance of the Gibbs measure $\mu_G$ under the finite-dimensional evolution to obtain certain space–time bounds of large deviation type.

Proposition 3.2. Let $T > 0$ be given. Then for every $0 \leq \sigma < \frac{1}{2}$, $2 \leq p < \frac{2}{\sigma}$ and $q < \infty$,

$$\mathbb{E}_{\mu_F} \left[ \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x} \right] < C(\sigma, p, q, T)$$

where $u_N = u_N^{(\phi)}$ is the solution of (4) corresponding to initial data $P_N \phi$ and the $L^q_t$ norm is taken on the interval $[0,T)$. In fact, there is the stronger distributional inequality

$$\mu_F \left( \{ \phi : \left\| (\sqrt{-\Delta})^{q} u_N \right\|_{L^p_tL^q_x} > \lambda \} \right) \lesssim \exp \left( -\lambda^c \right), \quad \lambda > 0, \quad N \geq 1,$$

for some $c > 0$.

Proof. Fix $\lambda_1 > 0$ to be determined later in the argument. Then, denoting $u = u_N^{(\phi)}$, we have

$$\mu_F \left( \{ \phi : \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x} > \lambda \} \right) \lesssim e^{\frac{1}{2} + \lambda_1^2} \mu_G \left( \{ \phi : \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x} > \lambda \} \right) + \mu_F \left( \{ \phi : \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x} > \lambda \} \cap \{ \phi : \left\| \phi \right\|_{L^p_tL^q_x} > \lambda_1 \} \right) =: (I) + (II).$$

(25)

To estimate term (I), we observe that for every $q_1 \geq \max\{p, q\}$ the Tchebyshev inequality and Minkowski inequality for integrals allow us to bound

$$\mu_G \left( \{ \phi : \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x} > \lambda \} \right)$$

by

$$\frac{1}{\lambda^{q_1}} \int \left\| (\sqrt{-\Delta})^{q} u \right\|_{L^p_tL^q_x}^{q_1} d\mu_G(\phi) \leq \left( \frac{T^{1/q}}{\lambda} \right)^{q_1} \left\| (\sqrt{-\Delta})^{q} \phi \right\|_{L^p_tL^q_x}^{q_1} \mathcal{M}_{\mu_G}(\phi) \lesssim_T \left( \frac{\sqrt{q_1}}{\lambda} \right)^{q_1} \left( \sum_{\varepsilon_n \leq N} \frac{\| e_n(x) \|_{L^p_x}^2}{\varepsilon_n^{2(1-\sigma)}} \right)^{1/2} \left\| \sum_{\varepsilon_n \leq N} \frac{\| e_n(x) \|_{L^p_x}^2}{\varepsilon_n^{2(1-\sigma)}} \right\|_{L^p_x}^{q_1/2}$$

(26)

where we use the invariance of the Gibbs measure $\mu_G$ under the truncated evolution (4). Using Minkowski’s inequality (since $p \geq 2$), we then have

$$\left(26\right) \lesssim \left( \frac{\sqrt{q_1}}{\lambda} \right)^{q_1} \left( \sum_{\varepsilon_n \leq N} \frac{\| e_n(x) \|_{L^p_x}^2}{\varepsilon_n^{2(1-\sigma)}} \right)^{q_1/2}.$$ 

(27)

Now, recalling the eigenfunction bounds (9), we have the bound

$$\sum_{n \in \mathbb{N}} n^{1-\frac{q}{p}} \leq C_0 + C_1 \sum_{n \geq N_0} n^{-(1-2\sigma)-\frac{4}{p}} < \infty,$$

(28)

where we have used the hypothesis $p < \frac{2}{\sigma}$.
Combining (28) with (27) gives
\[
\mu_G \left( \left\{ \phi : \left\| (\sqrt{-\Delta})^q u \right\|_{L^p_t L^q_x} > \lambda \right\} \right) \lesssim \left( \frac{q_1}{\lambda} \right)^{q_1} \tag{29}
\]
where the implicit constant is independent of \( N \). Optimizing (29) in \( q_1 \) then implies the bound
\[
(I) \lesssim \exp \left( \frac{1}{2 + \alpha} \lambda_1^{2+\alpha} \right) \exp \left( -\lambda^2 / (2e) \right). \tag{30}
\]
To estimate term (II), we fix \( q_2 > 2 + \alpha \) and again apply the Tchebyshev and Minkowski inequalities to bound the term
\[
\mu_F \left( \left\{ \phi : \left\| \phi \right\|_{L^{2+\alpha}_x} > \lambda_1 \right\} \right)
\]
by
\[
\frac{1}{\lambda_1^{q_2}} \int \left\| \phi \right\|_{L^{2+\alpha}_x}^{q_2} d\mu_F(\phi) \lesssim \frac{1}{\lambda_1^{q_2}} \left\| \phi \right\|_{L^{2+\alpha}_x}^{q_2} d\mu_F(\phi) \lesssim \left( \frac{\sqrt{q_2}}{\lambda_1} \right)^{q_2} \left( \sum_n \frac{\left\| e_n(x) \right\|_{L^{2+\alpha}_x}^2}{z_n^2} \right)^{q_2/2}.
\]
Appealing to the eigenfunction bounds (9) and the asymptotic representation (8) for \( z_n \), we estimate
\[
\sum_n n^{-1 - \frac{4}{\pi \alpha}} \lesssim C_0 + \sum_{n \geq N_0} n^{-1 - \frac{4}{\pi \alpha}} < \infty
\]
for \( N_0 \) sufficiently large. As a consequence we obtain
\[
\mu_F \left( \left\{ \phi : \left\| \phi \right\|_{L^{2+\alpha}_x} > \lambda_1 \right\} \right) \lesssim \left( \frac{\sqrt{q_2}}{\lambda_1} \right)^{q_2}.
\]
Minimizing the right-hand side over admissible values of \( q_2 \) we get the bound
\[
(II) \lesssim \exp \left( -\lambda_1^2 / (2e) \right). \tag{31}
\]
Combining (25) with (30) and (31) and optimizing in \( \lambda_1 \) then gives
\[
\mu_F \left( \left\{ \phi : \left\| (\sqrt{-\Delta})^q u \right\|_{L^p_t L^q_x} > \lambda \right\} \right) \lesssim \exp(-c\lambda^{4/2})
\]
as desired. This completes the proof of Proposition 3.2. \( \square \)

We will also require a slight refinement of Proposition 3.2 which is a consequence of similar arguments, and allows for more precise estimates.

**Proposition 3.3.** Let \( T, \sigma, p, q \) and \( (u_N) \) be as in Proposition 3.2. Then for all \( M, N \geq 1 \) with \( M < N \), one has the distributional inequality
\[
\mu_F^{(N)} \left( \left\{ \phi_N : \left\| (\sqrt{-\Delta})^q (u_N - P_M u_N) \right\|_{L^p_t L^q_x} > \lambda \right\} \right) < e^{-(\theta \lambda)^{\gamma}}
\]
where we have set \( \theta = T^{-\frac{1}{4}} M^{\frac{3}{2p} - \sigma} \).
4. Bilinear estimate on the nonlinearity

We now establish a bilinear estimate on the nonlinear term in the Duhamel formula (7) which controls interactions between high and low frequency components of the nonlinearity.

**Proposition 4.1.** Fix $0 \leq s \leq 1$, $b > \frac{1}{2}$ and $N \in \mathbb{Z}_+$. Then for every $\mu > 0$ we have the inequality

\[
\left\| \int_0^t e^{i(t-\tau)\Delta} (fg)(\tau) \, d\tau \right\|_{s,b} \lesssim \|f\|_{s,b} \|g\|_{s,b} \left( \sqrt{-\Delta} \right)^{5(2b-1)+\mu} \|g\|_{L_t^2 L_x^2}
\]  

(32)

for every $f$ and $g$ representable as

\[
f(t,x) = \sum_{n>N, m \in \mathbb{Z}} \hat{f}(n,m) e_n(x) e(mt),
\]

\[
g(t,x) = \sum_{n \leq N, m \in \mathbb{Z}} \hat{g}(n,m) e_n(x) e(mt).
\]

**Proof.** It suffices to establish (32) for $s = 0$. Since

\[
\|DF\|_{0,b} \sim \|(-\Delta)^{1/2} F\|_{0,b} = \|F\|_{1,b}
\]

the statement then clearly follows for $s = 1$ and we can then interpolate.

Let $\mu > 0$ be given. We begin by writing

\[
g = \sum_{K < N} g_K \quad \text{with} \quad g_K(t,x) = \sum_{n \sim K, m \in \mathbb{Z}} \hat{g}(m,n) e_n(x) e(mt).
\]

Fix $K \geq 1$ a dyadic integer, and estimate

\[
\left\| \int_0^t e^{i(t-\tau)\Delta} f g_K(\tau) \, d\tau \right\|_{0,b}.
\]  

(33)

Set $K_1 = K^5$ and let $J$ denote a partition of $\mathbb{Z}$ in intervals $I$ of size $K_1$. Write

\[
f g_K = \sum_{I,I' \in J, \text{dist}(I,I') \leq K_1} P_I(P_f f g_K) + \sum_{I,I' \in J, \text{dist}(I,I') > K_1} P_I(P_f f g_K) =: (I) + (II).
\]

By construction, the contribution of $(I)$ in (33) is clearly bounded by

\[
\left[ \sum_{I \in J} \left\| P_I \left( \int_0^t e^{i(t-\tau)\Delta} (P_f f g_K)(\tau) \, d\tau \right) \right\|_{0,b}^2 \right]^{1/2}
\]  

(34)

with $\tilde{I} = I$ or $\tilde{I} \in J$ a neighbor of $I$. Applying Lemma 2.5 to each term of (34) gives the estimate

\[
K_1^{2b-1+\epsilon} \left( \sum_{I \in J} \| P_I f \|_{L_t^2 L_x^{4\epsilon}}^2 \right)^{1/2} \lesssim K_1^{2b-1+\epsilon} \|g_K\|_{L_t^2 L_x^2} \left( \sum_{I \in J} \| P_I f \|_{L_t^{4\epsilon} L_x^4}^2 \right)^{1/2}
\]

and since by Lemma 2.3

\[
\| P_I f \|_{L_t^{4\epsilon} L_x^4} \lesssim K_1^\epsilon \| P_I f \|_{0,b}
\]

we obtain

\[
K_1^{2b-1+2\epsilon+\epsilon'} \| f \|_{0,b} \|g_K\|_{L_t^2 L_x^2} \lesssim K_1^{5(2b-1)+\mu} \| f \|_{0,b} \|g_K\|_{L_t^2 L_x^2}. 
\]  

(35)
Next we estimate the contribution of (II) in (33), which will appear as an error term. This contribution may certainly be bounded by \( \| (II) \|_{L^2_{x,t}} \). Fix \( t \) and write \( f(x, t) = \sum_{n \geq 1} f_n e_n(x) \). Clearly, we obtain by duality

\[
\left\| \sum_{I, J \in \mathcal{J}} P_I (P_J f g_K) \right\|_{L^2_x} \leq \max_{n \geq 1} \left( \left\| \sum_{|n-n'| > K_1} |a_n| \right\|_{L^2_{x,t}} \right)^{1/2}
\]

\[
= \sum_{n, n' \geq 1} |f_n| |a_{n'}| |M_{n, n'}|
\]

(36)

where we have denoted

\[
M_{n, n'} = \left| \langle e_n g_K, e_{n'} \rangle \right| \chi_{|n-n'| > K_1}.
\]

We therefore need to estimate the norm \( \| M \|_{\ell^2(\mathbb{Z}_+) \to \ell^2(\mathbb{Z}_+)} \) of the matrix \( M \). We will rely on the Shur bound

\[
\| M \| \leq \sup_n \left( \sum_{n'} |M_{n, n'}| \right)
\]

(since \( M \) is symmetric).

It remains to bound \( \langle e_n g_K, e_{n'} \rangle \). Write

\[
|z_n^2 - z_{n'}^2| \left| \langle e_n g_K, e_{n'} \rangle \right| = \left| \langle \Delta e_n g_K, e_{n'} \rangle - \langle e_n g_K, \Delta e_{n'} \rangle \right|
\]

and integrate by parts, using the Dirichlet boundary condition on \( B_2 \) to obtain the bound

\[
\left| (\nabla e_n \cdot \nabla g_K, e_{n'}) \right| + \left| (e_n \Delta g_K, e_{n'}) \right|.
\]

Hence, for \( |n - n'| \gg 1 \), we have

\[
|\langle e_n g_K, e_{n'} \rangle| \lesssim (n + n')^{-1} |n - n'|^{-1} \left[ \left( (\nabla e_n \cdot \nabla g_K, e_{n'}) \right| + \left| (e_n \Delta g_K, e_{n'}) \right| \right].
\]

(38)

Therefore, fixing \( n \in \mathbb{Z}_+ \)

\[
\sum_{n'} M_{n, n'} \lesssim \sum_{\{s: 2^n > K_1\}} \sum_{\{n: |n-n'| \gg 2^n\}} \left| (n + n')^{-1} \right| \left( (\nabla e_n \cdot \nabla g_K, e_{n'}) \right| + \left| (e_n \Delta g_K, e_{n'}) \right|
\]

\[
\lesssim \sum_{\{s: 2^n > K_1\}} \sum_{n' \geq 1} \frac{2^{-s/2}}{n} \left( \left( (\nabla e_n \cdot \nabla g_K, e_{n'}) \right|^2 + \left| (e_n \Delta g_K, e_{n'}) \right|^2 \right)^{1/2}
\]

\[
\lesssim \frac{K_1^{-1/2}}{n} \left( \| \nabla e_n \cdot \nabla g_K \|_{L^2_{x,t}} \| e_n \Delta g_K \|_{L^2_{x,t}} \right)
\]

where we used Cauchy–Schwarz and Parseval. The above quantity is then bounded by a multiple of

\[
\frac{K_1^{-1/2}}{n} \left( \| \nabla e_n \|_{L^2_{x,t}} \| \nabla g_K \|_{L^2_{x,t}} + \| \Delta g_K \|_{L^2_{x,t}} \right) \lesssim \frac{K^2}{K_1^{1/2}} \| g(t) \|_{L^2_{x,t}} \lesssim K^{-1} \| g(t) \|_{L^2_{x,t}}
\]

where we have used the choice of \( K_1 \).

This proves that

\[
(36) \lesssim \frac{1}{K} \| g(t) \|_{L^2_{x,t}} \left( \sum_{n \geq 1} |f_n|^2 \right)^{1/2} = \frac{1}{K} \| f(t) \|_{L^2_{x,t}} \| g(t) \|_{L^2_{x,t}}
\]

and

\[
\| (II) \|_{L^2_{x,t}} \lesssim \frac{1}{K} \| f \|_{L^2_{x,t}} \| g \|_{L^2_{x,t}}.
\]

(39)
Summing (35), (39) over dyadic \( K \) gives the estimate
\[
\| f \|_{0,b} \left( \sqrt{-\Delta} \right)^{5(2b-1)+\mu} g \|_{L^2_t L^q_x}
\]
as desired. \( \square \)

Remark 4.2. Note that the second factor on the right-hand side of (32) involves a classical space–time norm (rather than \( X^{s,b} \)-type norms). This will be important in the next section.

5. Proof of Theorem 1.1: convergence of the solutions of the truncated equations

In this section we establish Theorem 1.1 for radial NLS on the 2D ball and prove convergence of the sequence \( (u_N) \) in the space \( X^{s,b} \), almost surely in \( \omega \in \Omega \). Convergence in the space \( C_t H^s_x \) then follows from the embedding \( X^{s,b} \hookrightarrow L^\infty_t H^s_x \).

Proof of Theorem 1.1. Let \( 0 < s < \frac{1}{2} \) and \( T > 0 \) be given. We first establish the \( \mu_F \)-almost sure convergence of solutions \( (u_N) \) with \( N_k = 2^k \). Moreover, up to a covering argument partitioning the time interval, we may assume without loss of generality that \( T < \frac{1}{2} \).

Let \( \sigma \in (0, \frac{1}{2}) \), \( 1 \leq r < 2 \sigma \) and \( 1 \leq p, q < \infty \) be fixed parameters to be determined later in the argument. Fix \( N_0 < N_1 \), and for each \( \omega \in \Omega \), let \( u_{N_0}, u_{N_1} \) be the solutions of the truncated equation (4) with corresponding initial data \( P_{N_0} \phi(\omega) \) and \( P_{N_1} \phi(\omega) \).

Let \( B_{N_0} > 0 \) also be a parameter to be determined later satisfying \( B_{N_0} \lesssim N_0^{\gamma} \) for some \( \gamma > 0 \). Then, invoking (23) and Proposition 3.2, there exists a set \( \Omega(N_0, N_1) \) with
\[
\mu_F(\Omega(N_0, N_1)) \lesssim \exp(-B_{N_0}^c)
\]
such that for all \( \omega \in \Omega \setminus \Omega(N_0, N_1) \) one has the bounds
\[
\| P_{N_1} \phi^{(\omega)} - P_{N_0} \phi^{(\omega)} \|_{H^s_x} \lesssim N_0^{-\frac{1}{2}},
\]
(41) together with
\[
\max\left\{ \| u_{N_0} \|_{L^p_t L^q_x}, \| u_{N_1} \|_{L^p_t L^q_x} \right\} < B_{N_0},
\]
(42) and
\[
\max\left\{ \| (\sqrt{-\Delta})^\sigma u_{N_0} \|_{L^1_t L^q_x}, \| (\sqrt{-\Delta})^\sigma u_{N_1} \|_{L^1_t L^q_x} \right\} < B_{N_0}.
\]
(43)

Fixing \( \omega \in \Omega \setminus \Omega(N_0, N_1) \), we now estimate the \( X^{s,b}([0, T]) \) norm of the difference \( u_{N_1} - u_{N_0} \). For this, we will use an iterative argument on short time intervals. In particular, fixing a small value \( \eta = \eta(N_0) > 0 \), and partitioning the interval \( [0, T] \) into \( T/\eta \) intervals \( [t_i, t_{i+1}] \), with \( t_{i+1} - t_i = \eta \), we write
\[
u N_1(t) - u_{N_0}(t) = e^{i(t-t_i)\Delta}(u_{N_1}(t_i) - u_{N_0}(t_i))
- i \int_{t_i}^{t} e^{i(t-\tau)\Delta} \left[ P_{N_1}(|u_{N_1}|^q u_{N_1})(\tau) - P_{N_0}(|u_{N_1}|^q u_{N_1})(\tau) \right] d\tau
- i \int_{t_i}^{t} e^{i(t-\tau)\Delta} P_{N_0} \left[ |u_{N_1}|^q u_{N_1} - |u_{N_0}|^q u_{N_0}(\tau) \right] d\tau
\]
(44)
for \( t \in [t_i, t_{i+1}] \).

We now estimate the \( X^{s,b} \) norms of each term in (44). In what follows, all \( X^{s,b} \) and \( L^p_t \) norms will be taken on the time interval \( [t_i, t_{i+1}] \), unless otherwise indicated.
Using the unitarity of the linear propagator and the definition of the $X^{s,b}$ norm, the first term is estimated as
\[
\left\| e^{i(t-t_1)\Delta} (u_{N_1}(t_1) - u_{N_0}(t_1)) \right\|_{s,b} \lesssim \left\| u_{N_1}(t_1) - u_{N_0}(t_1) \right\|_{H^s}.
\] (45)

On the other hand, to estimate the second term in (44), we fix $s' \in (s, 1/2)$ and invoke Lemma 2.5, and the fractional product rule, which give the bound
\[
\left\| \int_{t_1}^t e^{i(t-t')\Delta} \left[ P_{N_1} \left( |u_{N_1}|^\alpha u_{N_1} \right)(\tau) - P_{N_0} \left( |u_{N_1}|^\alpha u_{N_1} \right)(\tau) \right] d\tau \right\|_{s,b}
\]
\[
\lesssim N_0^{-(s'-s)} \left\| (\sqrt{-\Delta})^{2b-1+s'+\epsilon} |u_{N_1}|^\alpha u_{N_1} \right\|_{L_t^{\frac{4}{3}+\epsilon} L_x^\frac{4}{3}}
\]
\[
\lesssim N_0^{-(s'-s)} \left\| u_{N_1} \right\|_{L_t^1 L_x^4} \left\| (\sqrt{-\Delta})^{2b-1+s'+\epsilon} u_{N_1} \right\|_{L_t^2 L_x^2} \left\| (\sqrt{-\Delta})^{\frac{4\alpha+1}{3}} \right\|
\]
\[
\lesssim N_0^{-(s'-s)} B_{N_0}^{\alpha+1},
\] (46)

provided that $b$ is chosen sufficiently close to $\frac{1}{2}$, $\epsilon > 0$ is chosen sufficiently small, and $\sigma$ is chosen large enough to ensure that
\[
2b - 1 + s' + \epsilon < \sigma,
\]

and the values $r_1, r_2 \geq 1$ satisfy $r_1 \leq p$ and $r_2 \leq r$ together with $\frac{4\alpha+1}{3} < q$ and
\[
\frac{3}{4} + \frac{3\epsilon}{\alpha} = \frac{\alpha}{r_1} + \frac{1}{r_2}.
\]

Combining the estimates (45) and (46), we obtain
\[
\left\| u_{N_1} - u_{N_0} \right\|_{X^{s,b}((t_1, t_1+\eta))} \lesssim \left\| u_{N_1}(t_1) - u_{N_0}(t_1) \right\|_{H^s} + N_0^{-(s'-s)} B_{N_0}^{\alpha+1}
\]
\[
+ \int_{t_1}^t e^{i(t-t')\Delta} P_{N_0} \left[ |u_{N_1}|^\alpha u_{N_1} - |u_{N_0}|^\alpha u_{N_0}(\tau) \right] d\tau \right\|_{s,b}.
\] (47)

On the other hand, from the assumption that $\alpha$ is an even integer we obtain the expansion
\[
|u_{N_1}|^\alpha u_{N_1} - |u_{N_0}|^\alpha u_{N_0} = (u_{N_1} - u_{N_0}) F_+(u_{N_0}, u_{N_1}, \bar{u}_{N_0}, \bar{u}_{N_1}) + (\bar{u}_{N_1} - \bar{u}_{N_0}) F_-(u_{N_0}, u_{N_1}, \bar{u}_{N_0}, \bar{u}_{N_1})
\]

with $F_+$, $F_-$ homogeneous polynomials of degree $\alpha$.

We will only estimate the $F_+$ term; the estimate for the $F_-$ term is identical. Performing dyadic decompositions in frequency, we obtain
\[
\left\| \int_{t_1}^t e^{i(t-t')\Delta} P_{N_0} \left[ (u_{N_1} - u_{N_0}) F_+ \right](\tau) d\tau \right\|_{s,b}
\]
\[
\lesssim \sum_K \left\| \int_{t_1}^t e^{i(t-t')\Delta} P_{N_0} \left[ (P_K (u_{N_1} - u_{N_0})) P_{K < \cdot \leq 2K} F_+ \right](\tau) d\tau \right\|_{s,b}
\]
\[
+ \sum_K \left\| \int_{t_1}^t e^{i(t-t')\Delta} P_{N_0} \left[ (P_{\leq K} (u_{N_1} - u_{N_0})) P_{K < \cdot \leq 2K} F_+ \right](\tau) d\tau \right\|_{s,b}
\]
\[
= \sum_K (I)_K + (II)_K.
\] (48)

To estimate the terms $(I)_K$, fix $\epsilon > 0$ small and note that by applying Proposition 4.1 followed by the fractional product rule we obtain
we obtain that

\[ K \lesssim \epsilon N \parallel_{L^{s,b}_t} \] 

for \( \epsilon > 0 \) sufficiently small and \( b > \frac{1}{4} \) close enough to \( \frac{1}{4} \) to ensure \( 8 < \frac{1}{8(2b-1)+2} \).

Turning to (II), we argue in a similar manner. In particular, again fix \( \epsilon > 0 \) small and note that by Lemma 2.5, the Hölder inequality and the fractional product rule, one has

\[
\left\| \int_0^t e^{i(t-\tau)A} P_{N_0} \left[ \left( P_{\leq K} (u_{N_1} - u_{N_0}) \right) P_{K < \leq 2K} F_+ \right] (\tau) \, d\tau \right\|_{s,b} 
\lesssim K^{-\epsilon} \left\| u_{N_1} - u_{N_0} \right\|_{s,b} \left\| (\sqrt{-\Delta})^{2b-1+2\epsilon} P_{K < \leq 2K} F_+ \right\|_{L^2_t L^s_x} 
\lesssim K^{-\epsilon} \eta^{\frac{1}{4}} \left\| u_{N_1} - u_{N_0} \right\|_{s,b} \left\| u \right\|_{L^8(0; L^s_x)} \left\| (\sqrt{-\Delta})^{2b-1+2\epsilon} u \right\|_{L^8_t L^8_x} 
\lesssim K^{-\epsilon} \eta^{\frac{1}{4}} B_{N_0}^{\alpha} \| u_{N_1} - u_{N_0} \|_{s,b} 
\text{(49)}
\]

for \( \epsilon > 0 \) sufficiently small and \( b > \frac{1}{4} \) close enough to \( \frac{1}{4} \) to ensure \( 8 < \frac{1}{8(2b-1)+2} \).

Combining (47), (48), (49) and (50) and evaluating the summation over \( K \) then gives the bound

\[
\left\| u_{N_1} - u_{N_0} \right\|_{s,b} \lesssim \left\| u_{N_1}(t_1) - u_{N_0}(t_1) \right\|_{H^s_x} + N_0^{-(s'-s)} + \eta^{\frac{1}{4}} B_{N_0}^{\alpha} \| u_{N_1} - u_{N_0} \|_{s,b} 
\text{(51)}
\]

so that choosing

\[
\eta = e B_{N_0}^{-4\alpha} \quad \text{and} \quad B_{N_0} = (c \log N_0)^{\frac{1}{4}}
\]

with \( c > 0 \) sufficiently small (depending on the implicit constant) gives the estimate

\[
\left\| u_{N_1} - u_{N_0} \right\|_{s,b} \lesssim \left\| u_{N_1}(t_1) - u_{N_0}(t_1) \right\|_{H^s_x} + N_0^{-(s'-s)/2} 
\text{(52)}
\]

It now remains to estimate the \( H^s_x \) norm appearing on the right side of (52). We argue iteratively, recalling the initial-time bound on \( u_{N_1} - u_{N_0} \) given by (41) and successively applying (52) to yield the bound

\[
\left\| u_{N_1} - u_{N_0} \right\|_{L^8_t L^8_x ([0,T]; H^s_x)} \lesssim C^{T/\eta} N_0^{-(s'-s)/4} 
\text{(53)}
\]

Substituting (53) into (52) and using the above choice of \( B_{N_0} \), we obtain the estimate

\[
\left\| u_{N_1} - u_{N_0} \right\|_{X^{s,b}([t_1,t_{1+1}])} \lesssim N_0^{-(s'-s)/4} 
\text{(54)}
\]

for all subintervals \([t_1, t_{1+1}] \subset [0, T]\). By a covering argument, one immediately gets

\[
\left\| u_{N_1} - u_{N_0} \right\|_{X^{s,b}([0,T])} \lesssim T N_0^{-(s'-s)/8} 
\text{(55)}
\]

for all initial data \( \phi^{(\omega)} \) with \( \omega \in \Omega \setminus \Omega (N_0, N_1) \).

Now, letting \( N_k = 2^k \) and setting

\[
\Omega_0 := \bigcap_{j \geq 1} \Omega (N_j, N_{j+1}),
\]

we obtain that \( u_{N_0} \) is a Cauchy sequence in \( X^{s,b}([0, T]) \) for all \( \omega \in \Omega \setminus \Omega_0 \). Moreover, recalling the bound (40), we have
\[ \mu_F(\Omega_0) \lesssim \sum_{j \geq J} \exp(-c \log N_j^{s/4a}) \]  

for all \( J \geq 1 \), and thus \( \mu_F(\Omega_0) = 0 \). The sequence \((u_{N_j})\) then converges in \( X^{s,b}(0, T) \) \( \mu_F \)-almost surely.

In order to conclude convergence of the full sequence \((u_N)\) a slightly more refined analysis is required. The essential difficulty is a consequence of the dependence of the excluded sets of initial data \( \Omega(N_j, N_{j+1}) \) on \( N_j \) and \( N_{j+1} \), since without passing to the subsequence \((u_{N_j})\) we cannot immediately conclude the convergence on the right side of (56).

In this case, fix a parameter \( C(p) \gg 1 \) to be determined, and note that for each \( N_0 \gg 1 \), we may consider

\[ M = (\log N_0)^{C(p)} \]

and replace the set \( \Omega \setminus \Omega(N_0, N_1) \) chosen in (40)–(43) by

\[ \Omega'(N_0) = \{ \omega \in \Omega: \phi^{(\omega)} - P_{N_0}\phi^{(\omega)} \|_{H^s_x} \lesssim N_0^{-1}, \|u_{N_0}\|_{L^p_t L^q_x} < B_{N_0}, \max_{N_0 \leq N < 2N_0} \|u_N - P_N u_N\|_{L^p_t L^q_x} < 1, \max_{N_0 \leq N < 2N_0} \|w_N - P_N w_N\|_{L^p_t L^q_x} < 1 \} \]

Recalling Proposition 3.2 and Proposition 3.3, we then have

\[ \mu_F(\Omega \setminus \Omega'(N_0)) < e^{-B_{N_0})/e} + 2B_{N_0} e^{-(M^{\frac{s}{p} - s})/e} \]

so that by choosing \( C(p) \) sufficiently large we obtain

\[ \mu_F(\Omega \setminus \Omega'(N_0)) < 3e^{-B_{N_0})/e} \]

Now, note that for \( N_0 \leq N_1 < 2N_0 \) we have

\[ \|u_{N_1}\|_{L^p_t L^q_x} \leq \|u_{N_1} - P_{M} u_{N_1}\|_{L^p_t L^q_x} + \|P_{M}(u_{N_1} - u_{N_0})\|_{L^p_t L^q_x} + \|u_{N_0} - P_{M} u_{N_0}\|_{L^p_t L^q_x} + \|u_{N_0}\|_{L^p_t L^q_x} \leq 2 + T^{1/q} \|P_{M}(u_{N_1} - u_{N_0})\|_{L^\infty_t} + B_{N_0} \leq 2 + T^{1/q} M^{1-s} \|u_{N_1} - u_{N_0}\|_{s,b} + B_{N_0} \leq (\log N_0)^C \|u_{N_1} - u_{N_0}\|_{s,b} + 2B_{N_0} \]

and

\[ \|\sqrt{-\Delta}\|_{L^p_t L^q_x} \leq \|\sqrt{-\Delta}\|_{L^p_t L^q_x} \|u_{N_1} - u_{N_0}\|_{L^p_t L^q_x} + \|\sqrt{-\Delta}\|_{L^p_t L^q_x} \|u_{N_0} - P_{M} u_{N_0}\|_{L^p_t L^q_x} + \|\sqrt{-\Delta}\|_{L^p_t L^q_x} \|u_{N_0}\|_{L^p_t L^q_x} \leq 2 + T^{1/q} M^{\sigma - s} \|P_{M}(u_{N_1} - u_{N_0})\|_{L^\infty_t} + B_{N_0} \leq 2 + T^{1/q} M^{1+\sigma - s} \|P_{M}(u_{N_1} - u_{N_0})\|_{s,b} + B_{N_0} \leq (\log N_0)^C \|u_{N_1} - u_{N_0}\|_{s,b} + 2B_{N_0} \]

For \( \omega \in \Omega'(N_0) \), the analogue of (51) then becomes

\[ \|u_{N_1} - u_{N_0}\|_{s,b} \lesssim \|u_{N_1}(t_1) - u_{N_0}(t_1)\|_{H^s_x} + \eta^{1/4} B_{N_0}^{\alpha} \|u_{N_1} - u_{N_0}\|_{s,b} + (\log N_0)^C \|u_{N_1} - u_{N_0}\|_{s+1}^{\alpha + 1} + N_0^{-\delta(\delta - s)} B_{N_0}^{\alpha + 1} \]

It then follows that

\[ \|u_{N_1} - u_{N_0}\|_{s,b} \lesssim \|u_{N_1}(t_1) - u_{N_0}(t_1)\|_{H^s_x} + (\log N_0)^C \|u_{N_1} - u_{N_0}\|_{s+1}^{\alpha + 1} + N_0^{-\delta(\delta - s)} \]

and thus (52)–(55) hold as before. \( \Box \)
Remark 5.1. As we pointed out, our assumption that \( \alpha \in 2\mathbb{Z}_+ \) in (1) is merely technical, though we would assume \( \alpha \geq 2 \) for smoothness reasons. Alternatively, one could consider nonlinearities of the form

\[
F(u) = \mp(1 + |u|^2)^{\alpha/2}u, \quad \alpha > 0
\]

(cf. [15]).

The method described above may be carried out in higher dimension, leading to the analogue of Theorem 1.1 for the radial defocusing NLS on \( B_d \)

\[
iu_t + \Delta u - (1 + |u|^2)^{\alpha/2}u = 0
\]

provided \( \alpha < \frac{2}{d-2} \).

In 3D, the counterpart of Theorem 1.1 for the defocusing cubic NLS

\[
iu_t + |u|^2u = 0
\]

was established in [9] and seems to require a more delicate analysis.

6. The mass-critical focusing case

In this section we complete the proof of Theorem 1.2. As noted in the introduction, the essential ingredient is contained in the following proposition, which shows that restriction to a sufficiently small \( L^2_x \) ball leads to the construction of a well-defined Gibbs measure.

Proposition 6.1. The measure

\[
\exp\left(\int_{B_2} |\phi|^4 \, dx \right) X_{\|\phi\|_{L^2_x} < \rho} \mu F(\phi) \, d\mu F(\phi)
\]

is a bounded measure, provided that \( \rho > 0 \) is chosen sufficiently small.

Proof. Fix \( \rho > 0 \) to be determined. To establish the proposition, it suffices to show that there exists \( C > 1 \) such that for every \( \lambda \gg 1 \), we have

\[
\mu F\left( \{ \phi : \|\phi\|_{L^4_x} > \lambda, \|\phi\|_{L^2_x} < \rho \} \right) \lesssim e^{-C\lambda^4}.
\]

(60)

This will be possible by choosing \( \rho \) sufficiently small.

To estimate the left-hand side of (60), we begin by writing

\[
\left\| \sum_{n \geq 1} \frac{g_n(\omega)}{z_n} e_n \right\|_{L^4_x} \leq \sum_{M \geq 1} \left\| \sum_{n \sim M} \frac{g_n(\omega)}{z_n} e_n \right\|_{L^4_x}
\]

(61)

where the summation in \( M \) is taken over dyadic integers.

For each \( M \geq 1 \) dyadic, choose \( j \in \mathbb{Z} \) such that \( M \sim 2^j (\lambda/\rho)^2 \), and define

\[
\sigma_M = \frac{1}{j^2}.
\]

Then

\[
\sum_{M \geq 1} \sigma_M \lesssim 1
\]

and therefore the condition

\[
\left\| \sum_{n \geq 1} \frac{g_n(\omega)}{z_n} e_n \right\|_{L^4_x} > \lambda
\]

(62)

implies
\[ \left\| \sum_{n=M} g_n(\omega) \right\|_{L^4_x} \sigma_M \lambda \]

for some \( M \geq 1 \).

To proceed, we consider an additional spatial decomposition, writing
\[ \sum_{n=M} g_n(\omega) \leq \sum_{k \geq 0} \sum_{n=M} g_n(\omega) \left\| e_n \right\|_{L^4_x}|\sim 2^{k+1}| \cdot \sum_{n>M} g_n(\omega) \left\| e_n \right\|_{L^4_x}|\sim 2^{k+1}| \cdot \sum_{n>M} \left\| e_n \right\|_{L^4_x}|\sim 2^{k+1}|. \]

The condition (62) implies that for some \( 0 \leq k \leq \log M \) we have
\[ \left\| \sum_{n=M} g_n(\omega) \right\|_{L^4_x}|x| \lesssim \sigma_M \lambda \leq \sqrt{2} (k+1)^{1/2}. \]

Let \( (a_n)_{n=1}^{\infty} \) be a sequence of arbitrary complex coefficients. One then has, using the Bessel function asymptotics, the estimate
\[ \left\| \sum_{n=M} a_n e_n \right\|_{L^4_x}|x| \lesssim \int_{r=2^{k+1}} \left( \sum_{n=M} |a_n| \right)^2 dr + \frac{1}{M^2} \left( \sum_{n=M} |a_n| \right)^2 \int_{r=2^{k+1}} dr = 2^{-k} M^{1/2} \left( \sum_{n=M} |a_n|^2 \right)^2. \]

Taking \( a_n = \frac{g_n(\omega)}{z_n} \) in this bound, it follows that if in addition to (62) we assume \( \| \phi \|_{L^2_x} < 2 \| \phi \|_{L^2_x} < \rho \), then
\[ \left\| \sum_{n=M} g_n(\omega) \right\|_{L^4_x}|x| \lesssim 2^{-k/4} M^{1/2} \rho. \]

Together with (64), this implies that for \( M \) and \( k \) satisfying (63) and (64) we have
\[ M > \left( \frac{\lambda}{\rho} \right)^2 \cdot \left( \frac{\log M}{k+1} \right)^2 \]
and thus
\[ j^{4/2} j > \frac{2^{k/2}}{k+1} \]
so that \( k \lesssim j \). In particular, we can therefore let \( j \geq 0 \) when writing \( M \sim 2^j \left( \frac{\lambda}{\rho} \right)^2 \).

We now assemble the above ingredients into the desired probabilistic estimate (60), for which we will make use of the estimate (11) for Gaussian processes. Noting that the bound \( |e_n(x)| \lesssim |x|^{-1/2} \) implies
\[ \mathbb{E}_\omega \left( \left\| \sum_{n=M} g_n(\omega) e_n \right\|_{L^4_x}|x| \right) \sim \left( \sum_{n=M} \frac{e_n^2}{n^2} \right)^{1/2} \left\| \sum_{n=M} \frac{1}{n^2} \right\|_{L^4_x}|x| \sim \frac{1}{\sqrt{M}} \]
apply (11) with
\[ X(\omega) = \sum_{n=M} g_n(\omega) e_n \quad \text{and} \quad \| \cdot \|_{L^4_x}|x| \sim \| \cdot \|_{L^2_x}|x| \]
By (66), we have \( \mathbb{E}[\| \|X\| \|] \sim \frac{1}{\sqrt{M}} \) and we take, according to (64)
\[ t = \frac{\sqrt{M} \sigma_M \lambda}{(k+1)^{1/2}} \sim \frac{2^{1/2} \lambda^2}{(k+1)^{1/2} j^2 \rho} \geq 1 \]
since \( k \lesssim j \).
We therefore conclude
\[ \|P_{\omega} \left[ \sum_{n \sim M} g_n(\omega) e_n \right] \|_{L^4_x(\|x\| \sim 2^k M^{-1})} \gtrsim \frac{\sigma M \lambda}{(k+1)^{1/2}} \lesssim e^{e^{-2j(k+1)^{1/2}}}. \] (67)

We now take the sum of (67) over \( j \geq 0 \) and \( 0 \leq k \lesssim j \), giving
\[ \mu_F(\{\phi: \|\phi\|_{L^4} > \lambda, \|\phi\|_{L^4} < \rho\}) \lesssim e^{-c\rho^{-2}\lambda^4} < e^{-C\lambda^4} \]
as desired for \( \rho \) small enough.

**Remark 6.2.** As we will show in Remark 6.4, the truncated Gibbs measure as defined in Proposition 6.1 becomes unbounded for \( \rho \) taken sufficiently large. We did not address here the issue of what is the optimal value of \( \rho \) for Proposition 6.1 to hold, which is an interesting question since it corresponds to a phase transition. Note that this problem was not even settled for \( d = 1 \) (cf. [13]).

**Remark 6.3.** In the \( d \)-dimensional setting, a similar argument applies for \( \alpha = \frac{4}{d} \), providing normalized Gibbs measures
\[ e^{\frac{1}{d} \|\phi\|_{L^d_x}^{d+2}} \chi(\|\phi\|_{L^d_x} < \rho) \mu_F(d\phi) \] (68)
for \( \rho \) sufficiently small (in the mass-subcritical case \( \alpha < \frac{4}{d} \), \( \rho \) can be taken arbitrarily).

Of course, one may replace the Hamiltonian by
\[ \int_{B_d} \left[ |\nabla \phi|^2 - (1 + |\phi|^2)^{\frac{d}{2} + 1} \right] dx \]
with \( \alpha \) as above, and consider the corresponding NLS
\[ iu_t + \Delta u + u(1 + |u|^2)^{\alpha/2} = 0. \] (69)

One obtains then the analogue of Theorem 1.2, provided moreover \( \alpha < \frac{d}{d-2} \) according to the comment at the end of Section 5.

**Remark 6.4.** Returning to Remark 6.2, the phenomenon is similar to the case \( d = 1, \alpha = 4 \), described in [13] (see also [10] for results on \( T^2 \), though the situation there is different).

For sufficiently large \( \rho \), the measures
\[ d\mu_N^{(N)} = e^{\frac{1}{d} \|\phi_N\|_{L^d_x}^{d+2}} \chi(\|\phi_N\|_{L^d_x} < \rho) d\mu_F^{(N)} \] (70)
become unbounded. A priori, this may not rule out the possibility that their normalization has an interesting limit distribution with perhaps a well-defined Schrödinger dynamics. But this turns out not to be the case. The distribution \( \mu_N^{(N)} \) concentrates indeed on functions \( \phi_N \) for which
\[ \|\phi_N\|_{L^4_x(|x| < O(\frac{1}{\rho}))} = O(\rho) \] (71)
and hence, in the limit, \( |\phi_N|^2 \) exhibits a delta function behavior at \( x = 0 \).

Note that for such functions
\[ H(\phi_N) = \int_{B_2} \left[ |\nabla \phi_N|^2 - \frac{1}{4} |\phi_N|^4 \right] < CN^2 \|\phi_N\|_{L^4_x}^2 - cN^2 \|\phi_N\|_{L^4_x(|x| < O(\frac{1}{\rho}))}^4 < -CN^2 \rho^4 < 0 \] (72)
for \( \rho \) sufficiently large. Invoking Kavian’s extension of Glassey’s theorem (see [12]), it follows that the solution to the Cauchy problem
\[
\begin{aligned}
\left\{
\begin{array}{ll}
iu_t + Du + uu_t = 0, \\
u|_{t=0} = \phi_N
\end{array}
\right.
\end{aligned}
\]

blows up in finite time.

Let us verify (71), taking for \(\rho\) a sufficiently large fixed constant. We prove that
\[
\log \|\mu_G^{(N)}\| \sim \rho^4 N^2. \tag{73}
\]

Since clearly \(\|\phi_N\|_{L^4_\rho} \lesssim N^{1/2} \|\phi_N\|_{L^2} \lesssim \rho N^{1/2}\), the upper bound in (73) is clear. Conversely, write
\[
\|\mu_G^{(N)}\| > e^{\frac{1}{2} \rho^4 N^2} \|\mu_F^{(N)}\| \left\{ \|\phi_N\|_{L^4_\rho} < \rho, \|\phi_N\|_{L^2} > c\rho N^{1/2} \right\}. \tag{74}
\]

Since \(\|\phi_N(0)\| \lesssim N^{1/2} \|\phi_N\|_{L^4_\rho}\), we have
\[
\mu_F^{(N)} \left\{ \|\phi_N\|_{L^4_\rho} < \rho, \|\phi_N\|_{L^2} > c\rho N^{1/2} \right\}
\geq \text{mes} \left\{ \omega: \sum_{n=1}^N \left| \frac{g_n(\omega)}{z_n^2} \right|^2 < \rho^2 \text{ and } \sum_{n=1}^N \left| \frac{g_n(\omega)}{z_n} e_n(0) \right| > c'\rho N \right\}
\geq \text{mes} \left\{ \omega: |g_1(\omega)|, \ldots, |g_{[N/2]}(\omega)| < 1 \text{ and } g_{[N/2]+1}(\omega), \ldots, g_N(\omega) \sim c''\rho^2 N \right\}
> e^{-C\rho^2 N^2}. \tag{75}
\]

Hence, (73) follows from (74), (75) by taking \(\rho\) large enough.

It is obvious from (73) that \(\mu_G^{(N)}\) is concentrated on functions \(\phi_N\) for which
\[
\|\phi_N\|_{L^4_\rho} \sim \rho N^{1/2}. \tag{76}
\]

Finally, assuming \(\phi_N\) satisfies (76), we verify (71).

Write
\[
\|\phi_N\|_{L^4_\rho} \leq \sum_{|k|: 2^k < N} \int_{|x| \sim 2^k/N} |\phi_N(x)|^4 \, dx \leq \sum_k \|\phi_N\|_{L^2_\rho(x|\sim 2^k/N)}^2 \|\phi_N\|_{L^2(x|\sim 2^k/N)}^2
\]

and
\[
\|\phi_N\|_{L^\infty(x|\sim 2^k/N)} \leq \sum_{n=1}^N |\hat{\phi}_N(n)| \|e_n\|_{L^\infty(x|\sim 2^k/N)} \lesssim \|\phi_N\|_{L^2_\rho(x|\sim 2^k/N)} \lesssim \sqrt{\frac{N}{2^k}} \sum_{n=1}^N |\hat{\phi}_N(n)|
\lesssim N 2^{-k/2} \|\phi_N\|_{L^2} \lesssim \rho^{-k/2} N.
\]

Hence, (76) clearly implies (71).

References


